

Programming Distributed Systems Consistency and Conflict-free Replication

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KIDS OUT OF CONTROL?



Inconsistency might be the problem!

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Programming Distributed Systems



Overview

- What is consistency?
- How can we define and distinguish between different notions of consistency?
- How can we keep replicated data consistent under concurrent updates?
- What implications does a consistency model have for an application?



Goals of this Learning Path

In this learning path, you will learn

- to compare formal declarative models for different types of consistency
- to relate sequential and concurrent semantics of register and set data types
- to translate space-time diagrams to event graphs
- to distinguish different conflict resolution strategies of replicated data types
- to explain the pros and cons of state- vs operation-based replication strategies for replicated data types



Consistency



Consistency

- Distributed systems: "Consistency" refers to the observable behaviour of a system (e.g. a data store).
- Consistency model defines the correct behavior when interacting with the system.

Remark: Consistency in Database systems

- The distributed systems and database communities also use the term "consistency", but with different meanings.
 - C in ACID
 - Refers to the property that application code is sequentially safe
- What we discuss here, is closer to "isolation"

All material and graphics in this section are based on material by Sebastian Burkhardt (Microsoft Research)[2] and the survey by Paolo Viotti and Marko Vukolic [5].



Example: Shared Register

- Operations on registers
 - $\blacksquare \ rd() \to v$
 - $\bullet \ wr(v) \to ok$
- System architecture:





Implementation 1: Single-copy Register



- Single replica of shared register
- Forward all read and write requests



Implementation 2: Epidemic Register



- Each replica stores a timestamped value
- Reads return the currently stored value; writes update this value, stamped with current time (e.g. logical clock)
- At random times, replicas send stored timestamped value to arbitrary subset of replicas
- When receiving timestamped value, replica replaces locally stored value if incoming timestamp is later



Question

Can clients observe a difference between the two implementations (single-copy vs. epidemic)?

Assumptions:

- Asynchronous communication
- Fairness of transport
- "Randomly" generated values



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- "Randomly" generated values

Notions:

- Single-Copy Register: Linearizability
- Epidemic Register: Sequential Consistency



Consistency for key-value stores



When generalized to key-value stores (i.e. collection of registers), the epidemic variant guarantees

- Eventual Consistency (if sending a randomly selected tuple in each message)
- **Causal Consistency** (if sending all tuples in each message).



Consistency model

- Required for any type of storage (system) that processes operations concurrently.
- Unless the consistency model is linearizability (= single-copy semantics), applications may observe non-sequential behaviors (often called **anomalies**).
- The set of possible behaviors, and conversely of possible anomalies, constitutes the consistency model.



Consistency specifications



What is a replicated shared object / service?

- Examples: REST Service, file system, key-value store, counters, registers, ...
- \blacksquare Formally specified by a set of operations Op and either
 - a sequential semantics S, or
 - a concurrent semantics F



Sequential semantics

$$S: Op^* \times Op \to Val$$

- Sequence of all prior operations represents current state (with default initial value)
- Operation to be performed
- Returned value

Example: Register

$$\begin{split} S(\epsilon, rd()) &= undef \text{ (read without prior write is undefined)} \\ S(wr(2) \cdot wr(8), rd()) &= 8 \text{ (read returns last value written)} \\ S(rd() \cdot wr(2) \cdot wr(8), wr(3)) &= ok \text{ (write always returns ok)} \end{split}$$



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But what about the semantics under concurrency?



Histories

A history records all the interactions between clients and the system:

- Operations performed
- Indication whether operation successfully completed and corresponding return value
- Relative order of concurrent operations
- Session of an operation (corresponds to client / connection)



Concurrent semantics

Classically, histories are represented as sequences of calls and returns[3].

А	call wr(1)
А	ret ok
А	call rd
В	call wr(333)
В	ret ok
В	call rd
А	ret 1
С	call rd
В	ret 333
С	ret 1



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(E, op, rval, rb, ss) ↑

set of client operation events









○ rd() :1



labels event with operation labels event with the return value (E, op, rval, rb, ss) set of client operation events "returns-before" partial order = client-observable order

of operations; orders nonoverlapping intervals





wr(3):ok

rd() :3

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labels event with operation labels event with the return Session A value wr(1):ok(E, op, rval, rb, ss) rd() :1 set of client operation events "returns-before" partial order = client-observable order of operations; orders nonrd() :1 overlapping intervals "same session" equivalence class; partitions events into ses-

sions



An event graph represents an execution of a system.

- Vertices: events
- Attributes: label for vertices with information on the corresponding event (e.g. which operation, parameters, return values)
- Relations: orderings or groupings of events

Definition

An event graph G is a tuple (E, d_1, \ldots, d_n) where $E \subseteq Events$ is a finite or countably infinite set of events, and each d_i is an attribute or relation over E.



Histories as event graphs

A history is an event graph (E, op, rval, rb, ss) where

- ${\ensuremath{\,{\rm \circ }}}\ op: E \to Op$ associate operation with an event
- $rval: E \rightarrow Values \cup \{\nabla\}$ are return values (∇ denotes that operation never returns)
- *rb* is returns-before order
- ss is same-session relation



Hands-on: Timeline diagram vs. event graph





Solution: Timeline diagram vs. event graph



Event graph G = (E, op, rval, rb) with

$$E = \{a, b, c, d\}$$

$$op = \{(a, wr(1)), (b, wr(2)), (c, rd()), (d, rd())\}$$

$$rval = \{(a, ok), (b, ok), (c, 2), (d, 1)\}$$

$$rb = \{(b, d), (c, d)\}$$

$$ss = \{(a, a), (b, b), (c, c), (c, d), (d, d), (d, c)\}$$



When is a history correct / valid?

Common approach: Require linearizability

- Insert linearization points between begin and end of operation
- Semantics of operations must hold with respect to these linearization points
- Linearization points serves as justification / witness for a history
- Here: Consistency semantics beyond linearizability!



Specifying the Consistency Semantics I

- An execution is an account of what happened when executing the implementation
- A history defines the observable client interaction
- A specification is a "test" on histories
 - But how do we specify such a "test" / predicate?

Operational consistency model

- Provides an abstract reference implementation whose behaviors provide the specifications
- Well-studied methodology for proving correctness (e.g. simulation relations or refinement)
- Problem: Typically close to specific concrete implementation technique



Specifying the Consistency Semantics II

- An abstract execution is an account of the "essence" of what happened
 - Applicable to many implementations
 - Correctness criterion: History is valid if consistent with an abstract execution satisfying some consistency guarantees
- A *concrete execution* is the account of what happened when executing an actual implementation

Axiomatic consistency model

- Uses logical conditions on histories to define valid behaviors
- Allows to combine different aspects (here: consistency guarantees)



Decomposing abstract executions

Essence of what happened can be tracked down to two basic responsibilities of the underlying protocol:

- **Update Propagation:** All operations must eventually become visible everywhere
- 2 Conflict Resolution: Conflicting operations must be arbitrated consistently



Visibility

- Relation that determines the subset of operations "visible" to (and potentially influencing) an operation
- Describes relative timing of update propagation and operations

$$a \xrightarrow{vis} b$$

- Effect of operation *a* is visible to the client performing *b*
- Updates are concurrent if they are not ordered by visibility (i.e. if they cannot observe each other's effect)



Arbitration

 Used for resolution of update conflicts (i.e. concurrent updates that do not commute)

$$a \xrightarrow{ar} b$$

- Total order on operations
- Often solved in practice by using timestamps



Definition: Abstract Executions

An **abstract** execution is an event graph (E, op, rval, rb, ss, vis, ar) such that

- (E, op, rval, rb, ss) is a history
- vis is acyclic
- ar is a total order



Arbitration order: inc(): $ok_1 \rightarrow inc():ok_2 \rightarrow rd():1_3 \rightarrow rd():2_4$



Return Values in Abstract Executions

An abstract execution (E, op, rval, rb, ss, vis, ar) satisfies a sequential semantics S if

$$rval(e) = S(op(e), vis^{-1}.sort(ar))$$

Observed state = visible operations sorted by arbitration


Consistency guarantee

A consistency guarantee is a predicate or property of an abstract execution.

- Consistency model is collection of all the guarantees needed; histories must be justifiable by an abstraction execution that satisfies them all.
- Ordering guarantees ensure that the order of operations is preserved (under certain conditions).
- Transactions ensure that operation sequences do not become visible individually.
- Synchronization operations can enforce ordering selectively.



Important consistency models: Overview

$$\label{eq:Linearizability} \begin{split} & \mathsf{Linearizability} = \mathsf{SingleOrder} \land \mathsf{Realtime} \land \mathsf{RVal} \\ & \mathsf{SequentialConsistency} = \mathsf{SingleOrder} \land \mathsf{ReadMyWrites} \land \mathsf{RVal} \\ & \mathsf{CausalConsistency} = \mathsf{EventualVisibility} \land \mathsf{Causality} \land \mathsf{RVal} \\ & \mathsf{BasicEventualConsistency} = \mathsf{EventualVisibility} \land \\ & \mathsf{NoCircularCausality} \land \mathsf{RVal} \end{split}$$

RVal refers to ReturnValueConsistency



Eventual Consistency (Quiescent Consistency)

In any execution where the updates stop at some point (i.e. where there are only finitely many updates), then eventually (i.e. after some unspecified amount of time) each session converges to the same state.

- Often used in replicated data stores
- In essence: Convergence
- It says nothing about
 - when the replicas will converge
 - what the state is that they will converge to
 - what is allowed in the meantime
 - when there is no phase of quiescence
- Very weak guarantee \Rightarrow Difficult to program against



Eventual visibility

An abstract execution satisfies EventualVisibility if all events become eventually visible.

$$\forall e \in E : |\{e' \in E | (e \xrightarrow{rb} e') \land (e \xrightarrow{yis} e')\}| < \infty$$



Session guarantees

- When issuing multiple operations in sequence within a session, we usually expect additional properties (session consistency)
- Session Order: $so = rb \cap ss$



Read My Writes

Alice' session

It would be confusing if Alice would not see her own message.Fix: Require that session order implies visibility

$$so \subseteq vis$$



Monotonic Reads



- It would be confusing if Bob read Alice' message, but when he later read again, he would not see the message anymore
- Fix: Require that visibility is monotonic with respect to session order

$$vis \circ so \subseteq vis$$





- Alice and Bob post concurrent different values, and the write of Bob is arbitrated after the update of Alice.
- Charlie reads and sees Bob's message; then later, in the same session, he only sees the "earlier" message of Alice.
- **Fix:** Require that remote operations become visible after all operations that precede them in arbitration order

$$ar \circ (vis \cap \neg ss) \subseteq vis$$



Causality Guarantees

Axiomatic definition of happens-before relation:

$$hb = ((rb \cap ss) \cup vis)^+$$

- Captures session order and transitive closure of session order and visibility
- NoCircularCausality: *acyclic*(*hb*)
- CausalVisibility: $hb \subseteq vis$
- CausalArbitration: $hb \subseteq ar$
- Causality: CausalVisibility \land CausalArbitration



Causal Consistency

- Strongest model that can implemented in such a way as to be available even under (network) partitions
- Causal consistency implies all session guarantees with the exception of Consistent Prefix.

 $\textbf{CausalConsistency} = \mathsf{EventualVisibility} \land \mathsf{Causality} \land \mathsf{RVal}$



Strong Models

- Ensure a single global order of operations that determines both visibility and arbitration
- SingleOrder:

$$\exists E' \subseteq rval^{-1}(\nabla) : vis = ar \setminus (E' \times E)$$

- What this means: Arbitration and visibility are the same except for subset E' that represents incomplete operations that are not visible to any other operation.
- Assuming, arbitration order corresponds to (perfect global) timestamps, the SingleOrder implies that:
 - **1** An operation can only see operations with earlier timestamps.
 - 2 An operation must see all complete operations with earlier timestamps.



Linearizability vs. Sequential Consistency

Linearizability requires RealTime:

 $rb\subseteq ar$

Sequential consistency requires ReadMyWrites (restricted to sessions)

 To observe the difference between the two, clients must be able to communicate over some "side channel" that allows them to observe real time ordering.



Conclusion



- In this lecture: Consistency for single operations
- Other aspect: Consistency for groups of operations (transactions)
- Open problem: Can we safely mix and match different types of consistency?



Conflict-free Replicatd Data Types



Motivation

So far, we resolved conflicting updates (i.e. non-commutative updates) simply by sequencing operations using arbitration order (ar).

But sometimes, applications

- \blacksquare do not want to depend on a global order such as ar
- want to be made aware of conflicts
- want to resolve conflicts in a specific way



Example: Multi-value register





How can we determine the state?



visible state = sequence of visible operations, sorted by arbitration order

General conflict resolution



visible state = subgraph of visible operations



Formal model

Before:

$$S: Op^* \times Op \to Val$$

• "Current state" $Op^* =$ Sequence of all prior operations

Now:

 $F: Op \times \mathbb{C} \to Val$

• Operation context C = Event graph of visible operations



Revisited: Sequential semantics for registers

$$S: Op^* \times Op \to Val$$

$$\begin{split} S(wr(2) \cdot wr(8), rd()) &= 8 \text{ (read returns last value written)} \\ S(\epsilon, rd()) &= undef \\ S(rd() \cdot wr(2) \cdot wr(8), wr(3)) &= ok \text{ (write always returns ok)} \end{split}$$



Operation Context

An operation context is a finite event graph C = (E, op, vis, ar).

- Events in *E* capture what prior operations are visible to the operation that is to be performed.
- Models the situation at a single replica



Concurrent semantics for Multi-Value Register

$$F: Op \times C \to Val$$

$$\begin{array}{lcl} F_{mvr}(wr(x),C) &=& ok \\ F_{mvr}(rd(),C) &=& \{x| \text{ exists e in C such that } op(e) = wr(x) \\ &\quad \text{ and e is vis-maximal in C} \} \end{array}$$



Quizz: What do the read ops return?









Return values in Abstract Executions revisited

Previous lecture:

An abstract execution (E, op, rval, rb, ss, vis, ar) satisfies a sequential semantics S if

$$rval(e) = S(op(e), vis^{-1}.sort(ar))$$

Read-value consistency can also be defined wrt concurrency semantics

An abstract execution A = (E, op, rval, rb, ss, vis, ar) satisfies a concurrent semantics F if

$$rval(e) = F(op(e), A \mid_{vis^{-1}(e), op, vis, ar})$$

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Conflict-free Replicated Data Types (CRDTs) [4]

- Same API as sequential abstract data type, but with concurrency semantics
- Catalogue of CRDTs
 - Register (Laster-writer wins, Multi-value)
 - Set (Grow-Only, Add-Wins, Remove-Wins)
 - Flags
 - Counter (unlimited, restricted/bounded)
 - Graph (directed, monotone DAG)
 - Sequence / List
 - Map, JSON
- If operations are commutative, same semantics as in sequential execution
- Otherwise, need arbitration to resolve conflict



Specification: Replicated counter

- Operation *inc* commutes \Rightarrow No conflict resolution policy is needed • Value returned depends only on *E* and *op*, but not on *vis* and *ar*

$$F_{ctr}(rd(), (E, op, vis, ar)) = |\{e' \in E \mid op(e') = inc\}|$$



Semantics of a replicated Set or How to design a CRDT

• Sequential specification of abstract data type Set S:

 $\{ true \} \quad add(e) \quad \{ e \in S \}$ $\{ true \} \quad rmv(e) \quad \{ e \notin S \}$

- The following pairs of operations are commutative (for two elements e, f and $e \neq f$):
 - {true} add(e); add(e) $\{e \in S\}$
 - {true} add(e); add(f) $\{e, f \in S\}$
 - {true} rmv(e); rmv(e) { $e \notin S$ }
 - {true} rmv(e); rmv(f) $\{e, f \notin S\}$
 - {true} add(e); rmv(f) $\{e \in S, f \notin S\}$

 \Rightarrow For these ops, the concurrent execution should yield the same result as executing the ops in any order.



What are the options regarding a concurrency semantics for add(e) and rmv(e)?

- The operations add(e) and rmv(e) are *not* commutative
 - {true} add(e); rmv(e) $\{e \notin S\}$
 - {true} rmv(e); add(e) $\{e \in S\}$
- Options for conflict-resolution strategy when *concurrently* executing add(e) and rmv(e)
 - add-wins: $e \in S$
 - remove-wins: $e \notin S$
 - erroneous state (i.e. escalate the conflict to the user)
 - last-writer wins (i.e. define arbitration order through total order,
 - e.g., by adding totally- ordered timestamps)



Set Semantics





Formal Semantics for the Add-Wins Set

$$\begin{array}{lll} F_{aws}(add(x),C) &= ok \\ F_{aws}(rmv(x),C) &= ok \\ F_{aws}(rd(),C) &= \{x | \mbox{ exists e in C such that } op(e) = add(x) \\ & \mbox{ and there exists no e' in C such that } \\ & op(e') = rmv(x) \mbox{ and } e \ \frac{vis}{e'} e' \} \end{array}$$



Sets with "interesting" semantics

Grow-only set

- Convergence by union on element set
- No remove operation
- 2P-Set (Wuu & Bernstein PODC 1984)
 - Set of added elements + set of tombstones (= removed elements)
 - Add/remove each element once
 - Problem: Violates sequential spec
- c-set (Sovran et al., SOSP 2011)
 - Count for each element how often it was added and removed
 - Problem: Violates sequential spec



Take a break!

A Mathematician, a Biologist and a Physicist are sitting in a street cafe watching people going in and coming out of the house on the other side of the street. First they see two people going into the house. Time passes. After a while they notice three persons coming out of the house.

The Physicist: "The measurement wasn't accurate.".

The Biologist: "They have reproduced".

The Mathematician: "If now exactly one person enters the house then it will be empty again."



CRDTs: Strong Eventual Consistency

- Eventual delivery: Every update is eventually applied at all correct replicas
- *Termination:* Update operation terminates
- Strong convergence: Correct replicas that have applied the same update have equivalent state



How to implement CRDTs



State-based CRDTs: Counter



- Synchronization by propagating replica state
- Updates must inflate the state
- State must form a join semi-lattice wrt merge
- \Rightarrow Merge must be idempotent, commutative, associative



Join-semilattice

• A join-semilattice S is a set that has a join (i.e. a least upper bound) for any non-empty finite subset:

For all elements $x, y \in S$, the least upper bound (LUB) $x \sqcup y$ exists.

- A semilattice is commutative, idempotent and associative.
- A partial order on the elements of S is induced by setting $x \le y$ iff $x \sqcup y = y$.


Examples





Operation-based CRDTs



- Concurrent updates must commute
- Requires reliable causal delivery for CRDTs with non-commutative operations



Example: Add-wins Set (Observed-remove Set)





Optimized version of Add-wins Set



Possible to garbage-collect the tombstone after remove
Trick: Assuming causal delivery, a removed element will never be re-introduced (with the same id)[1]



Challenges with CRDTs

- Meta-data overhead for CRDTs that require causal contexts
 - Version vectors track concurrent modifications
 - Problematic under churn (i.e. when nodes come and go)
- Monotonically growing state with state-based approach
 - Infeasible for inherently growing data types such as sets, maps, lists with prevalent add
 - When removing elements, often tombstones are required for conflict resolution that relies on concurrency information
 - Requires garbage collection of tombstones when updates become causally stable
- Composability
 - CRDTs can be recursively nested (e.g. Maps, Sequences) or atomically updated in transactions
 - Which type of composability is preferable? What is the semantics of the composed entity?



Delta-based CRDTs

- State-based CRDTs suffer from monotonically growing state (lattice!)
- Op-based CRDTs require reliable causal delivery



Adoption of CRDTs in industry





Conclusion

- CRDTs provide Strong Eventual Consistency (sometimes even more)
- Properties of good conflict resolution
 - Don't loose updates/information!
 - Deterministic (independent of local update order)
 - Semantics close to sequential version
- Meta-data overhead can be substantial



Further reading I

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Further reading II

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